

Mechanical Engineers as Neurosurgeons: An Emerging Frontier in Precision Medicine

Roopsandeep Bammidi*, Durgaprasad Kelli, Santhosh Kumar Dubba and Sreeramulu Dowluru

Department of Mechanical Engineering, Aditya Institute of Technology and Management, India

ISSN: 2640-9690



Abstract

The shifting face of medicine is witnessing a remarkable combination of engineering and neurology. Mechanical engineers, who have spent their careers inventing machines and calculating forces, are suddenly entering the operating room not as surgeons, but as critical contributors to neurosurgical precision, planning and creativity. This study looks into the new paradigm in which mechanical engineering principles, techniques and technologies are changing neurosurgery through robotics, biomechanics, surgical simulation and tailored medical equipment. It highlights the problems, opportunities and ethical issues at this new crossroads of disciplines.

Keywords: Mechanical engineer; Neurosurgeon; Engineering principles; Technologies; Ethical issues

***Corresponding author:** Roopsandeep Bammidi, Department of Mechanical Engineering, Aditya Institute of Technology and Management, Tekkali, Andhra Pradesh, India

Submission:  April 15, 2025

Published:  April 23, 2025

Volume 6 - Issue 1

How to cite this article: Roopsandeep Bammidi*, Durgaprasad Kelli, Santhosh Kumar Dubba and Sreeramulu Dowluru. Mechanical Engineers as Neurosurgeons: An Emerging Frontier in Precision Medicine. *Evolutions Mech Eng.* 6(1). EME.000628. 2025. DOI: [10.31031/EME.2025.06.000628](https://doi.org/10.31031/EME.2025.06.000628)

Copyright@ Roopsandeep Bammidi, This article is distributed under the terms of the Creative Commons Attribution 4.0 International License, which permits unrestricted use and redistribution provided that the original author and source are credited.

Introduction (Bridging Brain and Machine)

Neurosurgery is at the pinnacle of medical accuracy, requiring sub-millimetre precision, real-time responsiveness and a thorough understanding of the brain's complicated anatomy. In contrast, mechanical engineering is a field that focuses on accuracy, control and the analytical study of dynamic systems. The collaboration between these disciplines is not only unavoidable, but also necessary, as modern neurosurgery increasingly relies on equipment and methodologies from mechanical design, robotics and biomechanical modeling. Though the idea of mechanical engineers becoming neurosurgeons may be a metaphor, their participation in the neurosurgical process from pre-operative planning to intra-operative aid and post-operative rehabilitation is real. Engineers are now creating micro-manipulable robotic arms, haptic feedback systems for training and neural implants with micromechanical accuracy. These technologies have revolutionized not only the manner in which neurosurgery is performed, but also the individuals performing it.

Recent advances in neurosurgery technology show a strong integration of mechanical engineering ideas, particularly in implantable devices, simulation environments and predictive modeling software. Ghanbari MM [1] represents a significant advancement in implant technology, with the invention of small wireless neural implants that record and transfer brain activity from peripheral nerves. This invention emphasizes wire lessness and downsizing as critical design aspects, reflecting a greater emphasis on little intervention, long-term monitoring and brain interfacing. Bici M et al. [2] developed a force feedback system specifically for use in virtual reality-based surgical simulations to facilitate such hardware developments. Their technology, which combines finite element analysis with virtual prototyping, enhances preoperative planning and surgeon training by delivering a more immersive and physically accurate simulation of surgical situations.

Along with these mechanical devices, physical modeling-based machine learning technologies are becoming the foundation for neurosurgical planning. Salehi Y et al. [3] provide PhysGNN, a physics-based graph neural network model for estimating soft tissue

deformation during image-guided neurosurgery. This strategy significantly improves the accuracy of preoperative simulations by taking into account complex biomechanical interactions. Benam A et al. [4] investigate the biomechanical response of brain tissues using the Ogden model and introduce alternative constitutive frameworks that may better represent the non-linear elastic behavior of neural tissues during surgical manipulation. These modeling initiatives provide critical foundations for safer and more reliable neurosurgical procedures. The intersection of soft robotics and tactile simulation is also emerging. Thurner P et al. [5] explore the development of dynamic tactile synthetic tissues using soft robotic components to create hybrid surgical simulators. These systems are intended to increase the realism of training systems by simulating the mechanical and tactile qualities of human tissue. Similarly, Karimzadeh R et al. [6] underline the importance of haptic technology in neurosurgery training, having developed a bipolar electrocautery simulator that uses haptic feedback to recreate genuine real-time brain surgery circumstances. Boutin J et al. [7] underline the importance of tactile engagement by describing a pilot study of smart haptic gloves used in VR simulation training for external ventricular drain insertion, demonstrating how wearable haptics improve psychomotor learning and procedure accuracy.

In the context of in vivo study, Nia HT et al. [8] established an excellent procedure for measuring solid stress within brain tissue using compression and imaging technologies in mice models. This contribution is critical for understanding the mechanical environment in the brain, particularly in tumour investigations and hydrocephalus. Finally, two articles by Gomez ED et al. [9] highlight the importance of haptic feedback in robotic surgery. Their findings show that including instrument vibration feedback in simulation training significantly reduces cognitive workload and improves surgical performance in residents during real-time procedures, emphasizing the educational and ergonomic benefits of engineering solutions in high-stakes medical settings. These researches, taken together, provide a cohesive picture: mechanical engineering is transforming neurosurgery rather than simply allowing it. From implant design and virtual simulation to biomechanical modeling and training optimization, the junction of these professions is redefining what it means to prepare for and perform neurosurgical operations [10].

Engineering Tools in the Surgeon's Arsenal

Mechanical engineers are responsible for some of the most significant technological advances in neurosurgery:

A. Robotic assisted surgery: Accurate mechanical devices such as the ROSA® robot and the Da Vinci Surgical System have transformed neurosurgery. Mechanical engineers design the kinematics, actuation mechanisms and feedback loops of these systems. They ensure that these robots can navigate the complicated and changeable brain environment with precision that the human hand cannot match.

B. Biomechanical modeling of brain tissue: Most neurosurgical techniques are based on an understanding of

the mechanical behavior of brain tissue. Engineers construct computational models that predict how the brain will deform during surgery, allowing for real-time navigation and minimizing collateral harm. Finite Element Analysis (FEA), a mechanical engineering standard, used to predict these deformations and maximize surgical outcomes.

C. Surgical simulation and haptics: Engineers who develop high-fidelity simulators make it possible to educate future neurosurgeons using virtual settings. These gadgets provide force feedback and enable the safe execution of complex tasks. The contribution of mechanical engineers in developing realistic tissue contact models and force-feedback devices is critical to the simulators' performance.

D. Implants and medical devices: Neural implants, spinal implants and shunt systems are typically mechanical. Engineers are responsible for these devices' mechanical design, fatigue testing and material optimization. Their understanding of fluid dynamics is also critical in the design of cerebrospinal fluid diversion systems and vascular stents.

Training and Transdisciplinary Education

As the lines melt, a new generation of hybrid professionals emerges. Many higher education institutions are offering dual degrees in biomedical engineering with specializations in neurosurgery or neuro-engineering. Mechanical engineers who want to work in this sector should study neuroanatomy, neurophysiology and imaging, whereas neurosurgeons should learn about robots, systems modeling and data science. The best neurosurgeon of the future may be a mechanical engineer by training, capable of not only performing surgery but also designing the equipment they use. Programs such as hands-on cadaveric training for engineers and OR fellowships are helping to reduce the experience gap between specialties.

Ethical Considerations and Future Directions

The inclusion of mechanical engineering into neurosurgery raises additional ethical considerations. Who is accountable if an autonomous robotic system makes a mistake? How can we assure transparency and safety when engineers without medical licenses create equipment that interacts directly with the brain?

The above are the types of questions that highlight the importance of cross-disciplinary accountability, certification, and regulation. Mechanical engineers will play a larger role in neurosurgery in the future, particularly in the following areas: Independent surgical navigation Brain-Machine Interface (BMI), Intraoperative biomechanics in real time, customized surgical robots, Neuro-prosthetic control systems. These developments will not only broaden the area of neurosurgeons' practice, but may also lead to a shift in the profession's definition.

Conclusion (From Wrenches to Scalpels)

The union of mechanical engineering and neurosurgery exemplifies the future of precision medicine, in which

interdisciplinary innovation is the norm rather than the exception. Mechanical engineers are becoming essential collaborators in the healing process as the human brain becomes more accessible through technological windows. The operating room of the future will be both a mechanical design laboratory and a forum for biological intervention, blurring the lines between machine and brain, hand and instrument, engineer and physician.

References

1. Ghanbari MM (2024) Miniature wireless neural implants. EECS Department, University of California, Berkeley, USA.
2. Bici M, Guachi R, Bini F, Mani SF, Campana F, et al. (2024) Endo-surgical force feedback system design for virtual reality applications in medical planning. *International Journal on Interactive Design and Manufacturing (IJIDeM)* 18: 5479-5487.
3. Salehi Y, Giannacopoulos D (2021) PhysGNN: A physics-driven graph neural network-based model for predicting soft tissue deformation in image-guided neurosurgery. *arXiv Preprint arXiv: 2109.04352*.
4. Benam AA, Destrade M, Saccomandi G (2024) Modelling brain tissue elasticity with the Ogden model and an alternative family of constitutive models. *arXiv Preprint arXiv: 2407.08372*.
5. Thurner P, Maier J, Kaltenbrunner M, Schrempf A (2024) Dynamic tactile synthetic tissue: From soft robotics to hybrid surgical simulators. *Advanced Intelligent Systems* 6(12):
6. Karimzadeh R, Sheikh J, Azarnoush H, Arabi H (2023) Design and implementation of brain surgery bipolar electrocautery simulator using haptic technology. *Iranian Journal of Science and Technology, Transactions of Electrical Engineering* 47: 859-869.
7. Boutin J, Kamoopuri J, Faieghi R, Chung J, Ribaupierre S, et al. (2024) Smart haptic gloves for virtual reality surgery simulation: A pilot study on external ventricular drain training. *Frontiers in Robotics and AI* 10: 1273631.
8. Nia HT, Datta M, Seano G, Zhang S, Ho WW, et al. (2020) *In vivo* compression and imaging in mouse brain to measure, the effects of solid stress. *Nature Protocols* 15(8): 2321-2340.
9. Gomez ED, Husin HM, Dumon KR, Williams NN, Kuchenbecker KJ (2024) Simulation training with haptic feedback of instrument vibrations reduces resident workload during live robot-assisted sleeve gastrectomy. *Surgical Endoscopy* 39(3): 1523-1535.
10. Bammidi R, Dowluru S (2024) Dental sciences: The role of mechanical engineers. *Medicon Dental Sciences* 4(2): 1-2.