Production Scheduling in Block Caving with Consideration of Material Flow

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Abstract

Block-cave mining has become more popular in the last few years and the trend is expected to continue. The operating costs in this mining method could be as low as for open-pit mining; however, production scheduling for such an operation is complicated, mainly because of the production uncertainties resulted from the material flow. The material flow uncertainties should be considered in the production schedule to achieve a realistic mine plan. This research uses stochastic optimization for production scheduling in block-cave mining; the proposed model maximizes the net present value of the mining project while minimizing the production-grade deviations from a target grade. Some scenarios are considered to capture the material flow uncertainties. Testing the model for a real case block-cave mining operation shows that the proposed model can take the material flow uncertainties into the production schedule to achieve more reliable plans; the optimum production schedule is accomplished based on different scenarios which can happen in the real operations. The model also calculates the optimum height of draw as part of the optimization.

Introduction

Any planning and financial analysis in a mining project depend on production schedule in which the amount of ore and waste removal is determined in each period. An optimum realistic production schedule can significantly improve the overall practicality and profitability of the project. Block-cave mining operation is involved with uncertainties which cannot be ignored in the production scheduling; while the caving is occurring, the flow of material (which happens because of the gravity) can be unpredictable. The flow of material will result in grade and tonnage uncertainties in the production during the life of mine. Numerical methods are useful tools to model the material flow. Stochastic optimization can capture the uncertainty of material flow while optimizing the production schedule.

Production schedule in a block-cave mining operation can be investigated from different levels of resolutions: cluster level, draw point level, or slice level [1]. In this research, the slices are the smallest production units. The output of the production schedule at this level would be the periods in which each of the slices within a draw column is extracted and sent to the processing plant. These decisions are made based on the defined goal(s) in the objective function while considering the limitations of the operations as the constraints of the model. The proposed production scheduling model is a stochastic optimization model in which the net present value of the project is maximized during the life of the mine while the deviations from a target production grade are minimized. Different scenarios of the grade for the slice model are generated to capture the uncertainty of the production-grade which exists because of the material flow during production.

Block Caving

Currently, most of the surface mines work in a higher stripping ratios than in the past. In some conditions, a surface mine can be less attractive to operate, and underground mining is used instead. These conditions are (i) too much waste has to be removed in order to access the ore (high stripping ratios), (ii) waste storage space is limited, (iii) pit walls fail, or (iv) environmental considerations could be more important than exploitation profits [2]. Among underground methods, block-cave mining, because of its high production rate and low operating costs, could be considered as an appropriate alternative. Projections show that 25 percent of global copper production will come from underground mines by 2020. Mining companies are looking for an underground method with a high rate of production, similar to that of open-pit mining. Therefore, there is an increased interest in using block-cave mining to access deep and low-grade ore bodies. A schematic view of block cave mining is shown in Figure 1.

Literature Review

There is a significant amount of research on production scheduling in mining operations, mostly in open-pit mining [2]. In block-cave mining, the production schedule determines which
draw points to be opened/closed in each period, which slices to be extracted, what the best direction for mining development is, and what is the production rate and the production-grade during the life of mine. A detailed literature review of production scheduling in block-cave mining can be found in Khodayari & Pourrahimian [3].

Compare to open pit mining, production schedule in block-cave mining is more complicated to be optimized, mainly because of the material flow and its uncertainties. Researchers have been trying to model the flow of material and how it can impact the production in cave mining for almost three decades. Numerical models [1,4,5]; pilot tests [6,7] and full scale experiments [8-10] have been used to study the flow of the material. Pilot models have many limitations and in most cases cannot describe the behavior of the flow. Full-scale methods are usually expensive to use. Numerical models can be more efficient and less expensive if they are properly modeled [11]. Used Pascal cone to understand the probabilities of blocks moving down as the production occurs in caving operations. Although this model was dependent on the cell size and the probabilities, it was shown that stochastic models could be used to present the behavior of material flow.

This research proposes a stochastic optimization model in which, the uncertainty of the material flow which results in production-grade uncertainty, is implemented in the production scheduling optimization. This optimum production schedule will not only maximize the NPV of the project but also minimize the deviation of the production-grade from a target grade in all scenarios.

Modeling

The proposed model maximizes the NPV of the mining project during the life of mine while trying to minimize the deviations of production grade from a defined target grade. To be able to capture the uncertainty of production in block-cave mining, the model is a stochastic optimization in which different scenarios of grade mixing are considered. The formulation of the objective function was inspired by a stochastic optimization model which was used by MacNeil & Dimitrakopoulos [12] for determining the optimal depth of transition from open pit to underground mining. The scenarios are defined based on the grade distribution in the mine reserve. Each scenario represents one circumstance that can happen during the production based on the flow of the material. Figure 2 shows the flow of the material and how it can impact the production.
While extracting from a draw point, the material can move not only from the column above (DC8) but also from the columns in its neighborhood (DC1... DC7) into the intended draw point. The unpredicted material movements during the caving are the main source of the uncertainties in the operations. A production schedule would be more realistic if the uncertainties are captured. As it was mentioned, the decision units for the production schedule are the slices; the slice model is built based on the resource block model, the column above each draw point is divided into slices. In this section, the mathematical programming model is presented in details.

**Notation**

**Indices:**

- \(t \in \{1,\ldots,T\}\) Index for scheduling periods
- \(s \in \{1,\ldots,S\}\) Index for individual slices
- \(dp \in \{1,\ldots,Dp\}\) Index for individual draw points
- \(d \in \{1,\ldots,D\}\) Index for individual draw points
- \(a \in \{1,\ldots,A\}\) Index for the adjacent draw points

**Variables:**

- \(X^i_{dp} \in [0,1]\) Binary decision variable that determines if slices \(l\) is extracted in period \(t\) \([X^i_{dp} = 1]\) for not \([X^i_{dp} = 0]\)
- \(Y^i_{dp} \in [0,1]\) Binary decision variable which determines whether draw point \(dp\) in period \(t\) is active \([Y^i_{dp} = 1]\) for not \([Y^i_{dp} = 0]\)
- \(Z^i_{dp} \in [0,1]\) Binary decision variable which determines whether draw point \(dp\) in period \(t\) (periods 1, 2,...,t) has started its extraction \([Z^i_{dp} = 1]\) for not \([Z^i_{dp} = 0]\)
- \(d^e_s \in [0,\infty)\) Excessive amount from the target grade (the metal content)
- \(d^f_s \in [0,\infty)\) Deficient amount from the target grade (the metal content)

**Model parameters:**

- \(g_d\) Copper (Cu) grade of slice \(s\)
- \(g_E\) Expected copper grade based on all scenarios
- \(ton_s\) Ore tonnage of slice \(s\)
- \(t_c\) Current period
- \(sl_{dp}\) Number of slices associated with draw point \(dp\)

**Input parameters:**

- \(TarGrade\) The target grade of production which is defined based on the production goals and processing plant’s requirements
- \(M_{min}\) Minimum mining capacity based on the capacity of the plant and mining equipment
- \(M_{max}\) Maximum mining capacity based on the capacity of the plant and mining equipment

**Objective function**

The objective function is defined as follows:

\[
\text{Maximize}_{t=1}^{T} \sum_{d=1}^{Dp} \sum_{s=1}^{S} \left( \text{Price} \times \text{Rec} \times \left( \frac{g_d \times \text{ton}_s}{100} \right) \right) - \sum_{t=1}^{S} \sum_{d=1}^{Dp} \left( \text{Cost} \times \text{Rec} \times \left( \frac{g_d \times \text{ton}_s}{100} \right) \right) \times X^i_{dp} \times (1 + \text{IntRate})
\]

The first part of the objective function maximizes the NPV of the project during the life of mine by finding the optimum sequence of extraction for the slices in the mine reserve. The second part minimizes deviations of the production-grade from the target grade in different scenarios during the life of mine; this is done by allocating penalties to the deviations that might happen in different scenarios.

**Constraints**

Operational and technical constraints of block-cave mining operations are considered to control the outputs of the optimizations model. Some decision variables depend on the number of draw points and the number of slices in each draw point.

**Logical constraints:** There are two sets of binary decision variables in the proposed model which will be required for defining different constraints. Logical constraints connect the continuous decision variables to the binary ones, each set contains two inequality equations.
Set 1: \( Y_{dp}^t \in \{0,1\}, \{dp \in Dp, t \in T\} \)

\( \forall t \in T \& dp \in Dp \rightarrow Y_{dp}^t - M \times \sum_{i=1}^{sl} X_{dp}^i \leq 0 \) (2)

\( \forall t \in T \& dp \in Dp \rightarrow \sum_{i=1}^{sl} X_{dp}^i - M \times Y_{dp}^t \leq 0 \) (3)

Set 2: \( Z_{dp}^t \in \{0,1\}, \{dp \in Dp, t \in T\} \)

\( \forall dp \in Dp \rightarrow DP_{dp}^t = \sum_{i=1}^{sl} Y_{dp}^i \) (4)

\( \forall t \in T \& dp \in Dp \rightarrow DP_{dp}^t - M \times Z_{dp}^t \leq 0 \) (5)

\( \forall t \in T \& dp \in Dp \rightarrow Z_{dp}^t - M \times DP_{dp}^t \leq 0 \) (6)

**Mining Capacity:** Mining capacity is limited based on the production goals and the availability of equipment.

\( \forall t \in T \rightarrow M_{min} \leq \sum_{t=1}^{sl} \text{ton}_{d} \times X_{dp}^i \leq M_{max} \) (7)

**Production-grade:** This constraint ensures that the production grade is as close as possible to the target grade in different scenarios. The deviations from the target grade for all scenarios in different periods of production during the life of mine are considered for this constraint.

\( \forall t \in T \& s \in S \rightarrow \sum_{t=1}^{sl} (g_{d} - G_{max}) \times \text{ton}_{d} \times X_{dp}^i + d_{-} - d_{+} = 0 \) (8)

**Reserve:** This constraint makes sure that not more than the mining resources can be extracted, the output of the model would be the mining reserve.

\( \forall s \in S \rightarrow \sum_{t=1}^{T} X_{dp}^i \leq 1 \) (9)

**Active draw points:** A limited number of draw points can be in operation at each period; the mining layout, equipment availability, and geotechnical parameters can define this constraint.

\( \forall t \in T \rightarrow \text{ActMin} \leq \sum_{t=1}^{dp} Y_{dp}^i \leq \text{ActMax} \) (10)

**Mining precedence (horizontal):** The precedence is defined based on the mining direction in the layout. Production from each draw point can be started if the draw points in its neighbourhood which are located ahead (based on the mining direction) have already started their production. Equation (11) presents this constraint.

\( \forall dp \in Dp \& t \in T \rightarrow A \times Z_{dp}^t - \sum_{v=1}^{Z} Z_{dp}^v \leq 0 \) (11)

Where \( A \) is the number of draw points in the neighbourhood of draw point \( dp \) which are located ahead (based on the defined advancement direction), and \( Z \) is the second set of binary variables.

**Mining precedence (vertical):** This constraint defines the sequence of extraction between the slices within the draw columns during the life of mine.

\( \forall dp \in Dp \& \forall s \in S \& t \in T \rightarrow X_{dp}^i \leq \sum_{t=1}^{sl} X_{dp}^{i-1} \) (12)

This equation ensures that in each period of \( t \), slices associated with draw point \( dp \) is extracted if slice \( s \) (based on the defined advancement direction) is already extracted in the periods before or during the same period (\( t \)).

**Continuous mining:** This constraint guarantees continuous production for each of the draw points during the life of mine. In other words, if a draw point is opened, it is active in consecutive years (with at least the minimum draw rate of \( DR_{Min} \)) till it is closed.

\( \forall dp \in Dp \& T \rightarrow Y_{dp}^t \leq Y_{dp}^{t-1} + (1 - Z_{dp}^t) \) (13)

**Draw rate:** The total production of each draw point in each period of \( t \) is limited to a minimum and maximum amount of draw rate.

\( \forall dp \in Dp \& t \in T \rightarrow DR_{min} \times Y_{dp}^t \leq \sum_{t=1}^{sl} \text{ton}_{d} \times X_{dp}^i \leq DR_{max} \) (14)

**Draw life:** Draw points can be in production during a certain time which is called draw life. The draw life is limited to the minimum and maximum years of operations by the following equation:

\( \forall dp \in Dp \rightarrow \text{MinDrawLife} \leq \sum_{t=1}^{T} Y_{dp}^t \leq \text{MaxDrawLife} \) (15)

**Solving the optimization problem**

The proposed stochastic model has been developed in MATLAB [13] and solved in the IBM ILOG CPLEX environment [14]. CPLEX uses branch-and-cut search for solving the problem to achieve a solution within the defined mip gap (or the closest lower gap). The case study in this research was solved by a gap of 3% (a feasible integer solution proved to be within three percent of the optimal).

**Case Study**

The proposed model was tested on a block-cave mining operation with 102 draw points. It was a copper-gold deposit with the total ore of 22.5 million tones and the weighted average grade of 0.85% copper. The draw column heights vary from 320 to 351...
meters. Figure 3 & Figure 4 show the draw points layout (2D) and a conceptual view of the draw columns (3D). Each draw column consists of slices with the height of 10 meters (33 to 36 slices for each draw column). In total, the model was built on 3,470 slices. The goal is to produce a maximum of 2 million tones of ore per year during the ten years of mine life. The details of the input parameters for the case study are presented in Table 1.

In this case study, different scenarios were defined by generating random numbers in MATLAB; a linear function was defined based on the original grades of the slices to produce different scenarios. The model was built in MATLAB (R2017a) and solved using IBM/CPLEX (Version 12.7.1.0). Also, the model was solved as a deterministic model in which there was no penalty for deviation from defined target grade. The production grade in different scenarios (stochastic model) and deterministic model is shown in Figure 5.

It can be observed that in all scenarios the production grade is as close as possible to the defined target grade during the life of mine. The deterministic model tries to maximize the NPV and the higher-grade ore is extracted at the first years of production and then the lower grades at the latter years. The mining capacity constraint regulates ore production, and the ramp-up and ramp-down are almost achieved in both stochastic and deterministic models (Figure 6 & Figure 7).

Table 1: Scheduling parameters for the case study.

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Value</th>
<th>Unit</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>T</td>
<td>10</td>
<td>Year</td>
<td>Number of periods (life of the mine)</td>
</tr>
<tr>
<td>Tmin</td>
<td>0</td>
<td></td>
<td>Minimum mining capacity per period</td>
</tr>
<tr>
<td>Mmax</td>
<td>2</td>
<td>Mt</td>
<td>Maximum mining capacity at the first year of production</td>
</tr>
<tr>
<td>Min Draw Life</td>
<td>0</td>
<td>Year</td>
<td>Minimum life of draw points</td>
</tr>
<tr>
<td>Max Draw Life</td>
<td>4</td>
<td>Year</td>
<td>Maximum life of draw points</td>
</tr>
<tr>
<td>DRMin</td>
<td>13,000</td>
<td>Tonne/year</td>
<td>Minimum draw rate</td>
</tr>
<tr>
<td>DRMax</td>
<td>75,000</td>
<td>Tonne/year</td>
<td>Maximum draw rate</td>
</tr>
<tr>
<td>Recovery</td>
<td>85</td>
<td>%</td>
<td>Recovery of the processing plant</td>
</tr>
<tr>
<td>Price</td>
<td>5,000</td>
<td>$/tonne</td>
<td>Copper price per tonne of copper</td>
</tr>
<tr>
<td>Cost</td>
<td>15</td>
<td>$/tonne</td>
<td>Operating cost per tonne of ore (Mining + Processing)</td>
</tr>
<tr>
<td>Int Rate</td>
<td>10</td>
<td>%</td>
<td>Discount rate</td>
</tr>
<tr>
<td>S</td>
<td>50</td>
<td></td>
<td>Number of scenarios</td>
</tr>
</tbody>
</table>

It can be observed that in all scenarios the production grade is as close as possible to the defined target grade during the life of mine. The deterministic model tries to maximize the NPV and the higher-grade ore is extracted at the first years of production and then the lower grades at the latter years. The mining capacity constraint regulates ore production, and the ramp-up and ramp-down are almost achieved in both stochastic and deterministic models (Figure 6 & Figure 7).
Horizontal precedence, which is the sequence of extraction between draw points, was achieved for both of models based on the defined V-shaped precedence (Figure 8 & Figure 9).

Vertical precedence determines the sequence of extraction between slices in each of draw columns. Figure 10 shows the sequence of extraction in draw column number 75. Extraction from this draw point starts from year 5 and ends at year 8; the sequence of extraction is from bottom to top, and the production is continuous which means that both the vertical precedence and continuous mining constraints were satisfied. The original height of draw column number 75 is 330.1 meters with the total ore of 212,397 tonnes which contains 34 slices. Based on the optimization results (Figure 10), the optimum height of draw or BHD (Best Height of Draw) was 260 meters with the optimum draw tonnage of 168,650; this means that 26 out of 34 slices are extracted during the life of mine.

Number of active draw points and number of new draw points which are opened in each year for both models are presented in Figure 11 & Figure 12. Comparing the new draw points to be opened in each year for two models, the stochastic model does not suggest big changes from one year to another while the deterministic model...
shows such a pattern. In other words, the results of the stochastic model are more practical than the deterministic model. A brief comparison among the original ore resource model, the results of the deterministic model, and the results of the stochastic model is presented in Table 2. For this case study, the mining reserve and the NPV of the project for both models are almost the same (-2% in ore reserve and 0.7% for NPV). The stochastic model takes longer to solve because of the number of decision variables and the number of constraints, more decision variables for the defining the deviations and more constraints for of the scenarios.

| Table 2: Comparing the original model with the deterministic and stochastic models results |
|-----------------------------------------------|-----------------|-----------------|
| Comparison item                              | Original Model (Mine Resource) | Mine Reserve |
|                                               | Deterministic Model | Stochastic Model |
| Ore tonnage (Mt)                              | 22.5              | 14              | 13.7 |
| Number of slices                             | 3,470             | 2,160           | 2,106 |

Discussion

Production scheduling for block-cave mining operations could be challenging because of the material flow uncertainties. In this research, a stochastic optimization model was proposed to maximize the NPV of the project while minimizing the production-grade deviations from the target grade. Results show that stochastic models are effective for block-cave production scheduling. Consequently, the production goals are achieved, the constraints of the mining project are satisfied, the uncertainty of the material flows captured, the optimum height of draw (best height of draw) is calculated as part of the optimization, and the net present value of the project is maximized. Unlike deterministic models which do not consider the uncertainty of the material flow, stochastic models can maximize the profitability of the project while minimizing the unexpected events. The future work will be on consideration of both grade and tonnage uncertainties in the production schedule as well as generating more realistic scenarios.

References


