ISSN: 2640-9739

Research Article

CFOA based Integrator Suitable for Analog Signal Processing



Praween K Sinha*, Mohit Kumar, Gautam Kunal Haruray and Neelam Sharma

Department of Electronics and Communication Engineering, Maharaja Agrasen Institute of Technology, India

*Corresponding author: Praween K Sinha, Department of Electronics and Communication Engineering, Maharaja Agrasen Institute of Technology, Sec-22, Rohini, New Delhi-110086, India

Submission:

August 25, 2018; Published:

October 30, 2018

Abstract

Current Feedback Operational Amplifier (AD844) uses a circuit design that emphasizes current-mode operation, which is inherently much faster than voltage-mode operation because it is less effected by stray node-capacitances. When fabricated using high-speed complementary bipolar processes, CFOA's can be orders of magnitude faster than other available feedback amplifiers ex. VFA's. With CFOAs, the amplifier gain may be controlled independently of bandwidth. All these constitutes the major advantages of CFOAs. Some new and more efficient active RC integrator circuit realizations, using minimum passive components grounded and a current feedback operational amplifier (CFOA) device are proposed. Integrator with Grounded passive components allow better usability in VLSI. Finally, experimental result by wave processing has been verified using Proteus software.

Keywords: Integrators; Current-feedback-operational-amplifiers; Current mode circuits

Introduction

Active - RC integrator circuit is widely used in analog computers, analog-to-digital converters and wave-shaping circuits. These circuits essentially fuse a ratio type (v1/v2) function involving an active device like the voltage operational amplifier, operational trans-conductance amplifier, current conveyor, and current feedback operational amplifiers [1-6]. But use of Current Feedback Operational Amplifier's has increased exponentially in past few years [3-5] because of the its distinctive characteristics, in comparison with traditional operational amplifiers, like inverting input with low input resistance, additional output with high output resistance, frequency range extension, and very fast large signal response (major advantages over the op-amp are the increased device bandwidth at higher slew-rate, and, accurate port tracking properties leading to a less sensitive design) [7-13]. Typically, these amplifiers perform on the complementary bipolar technology on heterogeneous symmetric p-n-p and n-p-n transistors. Experimental results on wave processing have been verified with Proteus simulation.

CFOA

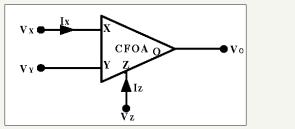


Figure 1: Current feedback operational amplifier (AD844).

The current feedback operational amplifier (CFOA) is a type of electronic amplifier which have current as inverting input, rather than voltage as in a conventional voltage-feedback operational amplifier (VFA). Figure 1 gives a representation of the amplifier with potential (Y) and current (X) inputs and potential (O) and current (Z) outputs.

A CFOA is a four terminal building block characterized by the following terminal equations.

$$\begin{aligned} \mathbf{V}_{\mathbf{X}} &= \mathbf{V}_{\mathbf{y}}, \, \mathbf{I}_{\mathbf{y}} &= \mathbf{0}, \, \mathbf{I}_{\mathbf{z}} &= \mathbf{I}_{\mathbf{x}}, \, \mathbf{V}_{\mathbf{0}} &= \mathbf{V} \\ \begin{bmatrix} I_{Y} \\ V_{X} \\ I_{Z} \\ V_{O} \end{bmatrix} &= \begin{bmatrix} 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} V_{Y} \\ I_{X} \\ V_{Z} \\ I_{O} \end{bmatrix}$$

These circuits showcase better performance, particularly higher speed and better bandwidth, than voltage mode operational amplifiers (VOA). The current feedback operational amplifier (CFOA) close-loop bandwidth is independent of its close-loop gain (provided that the feedback resistance is kept constant and much higher than the CFOA inverting input resistance) unlike VOA-based circuits, which are limited by a constant gain-bandwidth product. The CFOA block is preferred for low-voltage, low-power applications and is characterized by low voltage-transfer errors and high output driving current capability [1].

In this paper, new circuit models are developed by giving appropriate basic thought to the subject all in current mode. As a result, new integrator circuits have been developed having efficient performance and characteristics. New sets of circuit models

based on current mode approach, which have been developed are likely to find productive use in the field of modern electronics. This work offers some circuits having improved characteristics with respect to tenability, component count, integrability i.e. chip area economization. These circuits can be of great value in signal processing, communication and instrumentation area.

Generalised Scheme hor Generation of Different Types of Integrators

Mathematical Analysis

Integrator: Figure 2

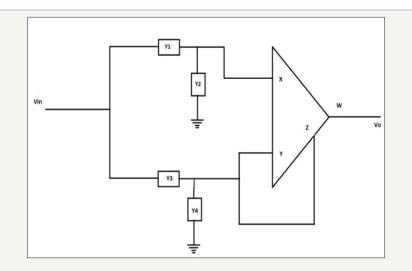


Figure 2: Integrator.

Analysis:
$$-V_x = Vy = V_{in}$$
, $I_v = 0$, $I_z = I_x$, $V_o = V_z$

$$I_z + V_v y_4 + (V_v - V_{in}) y_3 = 0$$

Thus,
$$V_v y_2 + (V_v - V_{in}) y_1 + I_x = 0$$

$$V_0 y_1 + (V_0 - V_{in}) y_3 + I_z = 0$$

$$V_0 y_2 + (V_0 - V_{in}) y_1 + I_z = 0$$

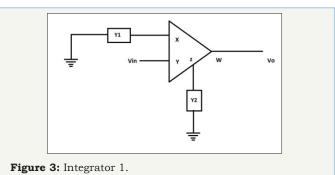
$$V_{o}y_{4}+(V_{o}-V_{in})y_{3}=V_{o}y_{2}+(V_{o}-V_{in})y_{1}$$

$$V_0 y_4 + V_0 y_3 - V_{in} y_3 = V_0 y_2 + V_0 y_1 - V_{in} y_1$$

$$V_{0}(y_4+y_3-y_2-y_1) = V_{in}(y_3-y_1)$$

$$\frac{Vo}{Vin} = \frac{(y1 - y3)}{(y2 + y1 - y3 - y4)} \tag{1}$$

Integrator 1: Figure 3



Analysis:
$$-V_x = V_y = V_{in}$$
, $I_y = 0$, $I_z = I_x$, $V_o = V_z$

$$V_2 = V_0$$

$$I_{x}+V_{in}y_{1}'=0$$

$$I_z = -V_0 y_2'$$

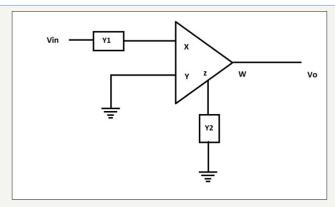
Applying KCL

$$-V_{0}y_{2}'+V_{in}y_{1}'=0$$

$$\frac{Vo}{Vin} = \frac{y2'}{y1'}$$

(2)

Integrator 2: Figure 4



(3)

Figure 4: Integrator 2.

Analysis:
$$-V_x = V_y = V_{in}$$
, $I_y = 0$, $I_z = I_x$, $V_o = V_z$

$$I_x = V_{in} y_1'$$

$$I_z = -V_0 y_2'$$

$$\frac{Vo}{Vin} = -\frac{y1'}{v2'}$$

Practical Working Cases

Case I (Integrator 1) Figure 5

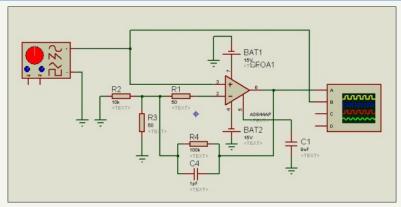


Figure 5: Schematic diagram case I.

$$y_1' = \frac{1}{R}, y_2' = sC$$

using Eq. (2)
 $\frac{Vo}{Vin} = \frac{R}{sC}$
When R=10K Ω , C= 9uF

$$\frac{Vo}{Vin} = \frac{L0K}{s \, 9uF}$$

$$\frac{Vo}{Vin} = \frac{1}{9 \times 10^{-10} \, s}$$
Figure 6

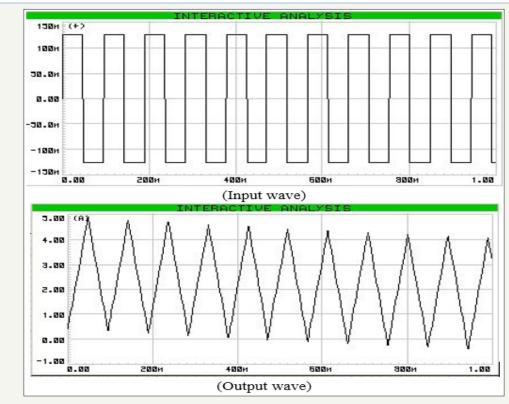


Figure 6: Simulation of case I.

Wave conversion at 10Hz by CFOA of Figure 5 using R=10K $\!\Omega$, C=9uF

Case II (Integrator 2) Figure 7

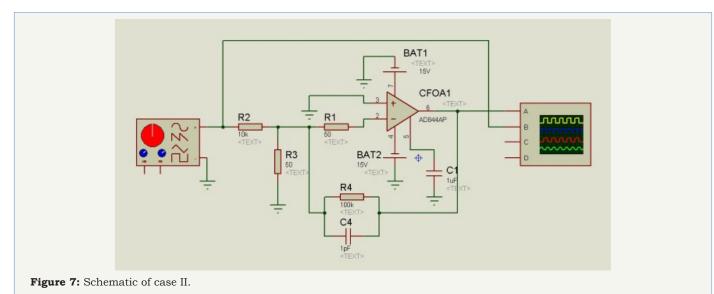
$$y_1' = , y_2' = sC$$

When $R=10K\Omega$, C=9uF

using Eq. (3)

$$\frac{Vo}{Vin} = -\frac{1}{RsC}$$

$$\frac{Vo}{Vin} = \frac{1}{RsC}$$



 $-\frac{1}{s \times 9 uF \times 10K}$

$$\frac{Vo}{Vin} = \frac{1}{9 \times 10^{-2} s}$$

Figure 8

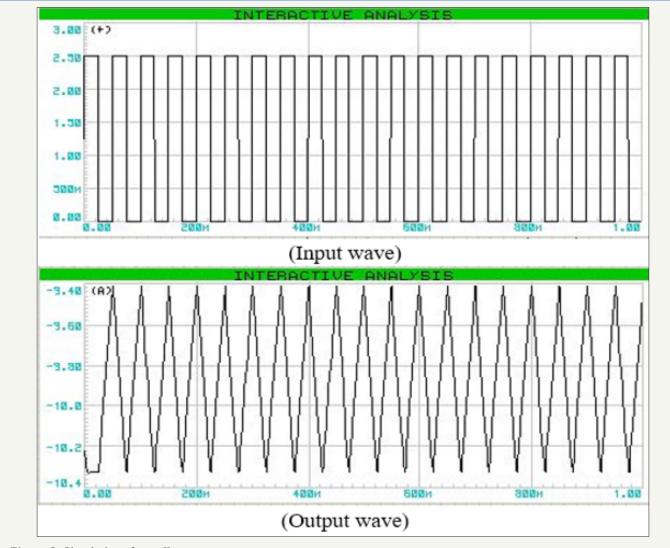


Figure 8: Simulation of case II.

Figure 10

Wave conversion at 10Hz by CFOA of Figure 7 using R=10K $\!\Omega$, C=9uF.

Case III (Integrator) Figure 9

$$y_{1} = \frac{1}{RI}, y_{2} = sC_{2}, y_{3} = 0, y_{4} = \frac{1}{R4}$$
using Eq. (1)
$$\frac{Vo}{Vin} = \frac{\frac{1}{RI} - 0}{\frac{1}{RI} - sC2 - \frac{1}{R4}}$$

$$\frac{Vo}{Vin} = \frac{\frac{1}{RI}}{\frac{R4 + R1.R4.SC2}{R1.R4}}$$

$$\frac{Vo}{Vin} = \frac{R4}{R4 - R1 + R1.R4.SC2}$$
When R₁= 100k, R₄=100k
$$\frac{Vo}{Vin} = \frac{100k}{100k - 100k + 100k \times 100k \times s.10^{-6} \, F}$$

$$\frac{Vo}{Vin} = \frac{10^{5}}{10^{4} \, s}$$

$$Vo = 10$$

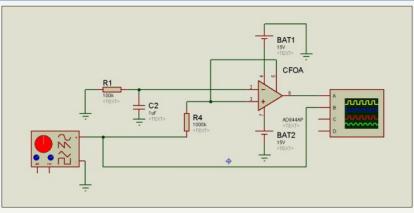
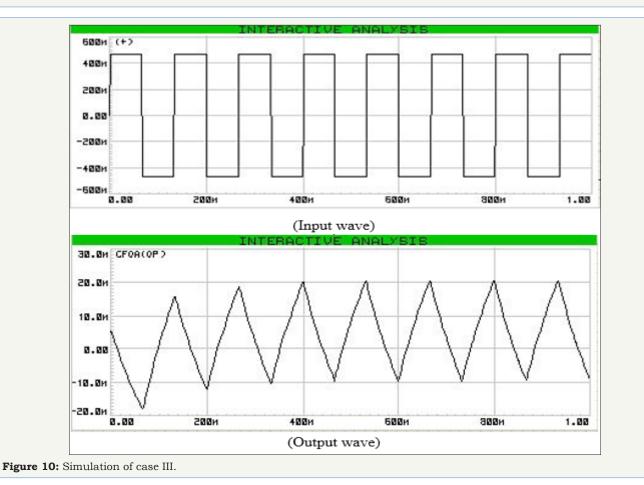


Figure 9: Schematic of case III.



Wave conversion at 10Hz by CFOA of Figure 9 using $R_{_1}\text{=}100k\Omega,$ $R_{_4}\text{=}100k\Omega$

Case IV (Integrator 2) Figure 11

When
$$y_1 = \frac{1}{R1}$$
, $y_2 = \frac{1}{R2}$, $y_3 = \frac{1}{R3}$, $y_4 = sC_4$ using Eq.(1)

$$\frac{Vo}{Vin} = \frac{\frac{1}{R1} - \frac{1}{R3}}{\frac{1}{R1} + \frac{1}{R2} - \frac{1}{R3} - sC4}$$

$$\frac{Vo}{Vin} = \frac{(R3 - R1)R2}{R2.R3 + R1.R3 - R1.R2 - R1.R2.R3.sC4}$$

When R_1 =1000kΩ, R_2 =100kΩ, R_3 =100kΩ, C_4 =1uf

$$\frac{V_O}{Vin} = \frac{(100k - 100k)100k}{(100k)^2 + 1000k.100k - 100k.1000k - 1000k.(100k)^2.1 \times 10^{-6} s}$$

$$\frac{Vo}{Vin} = \frac{-9}{1-s}$$

Figure 12

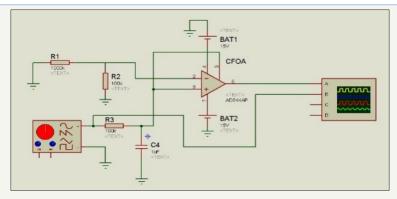


Figure 11: Schematic of case IV.

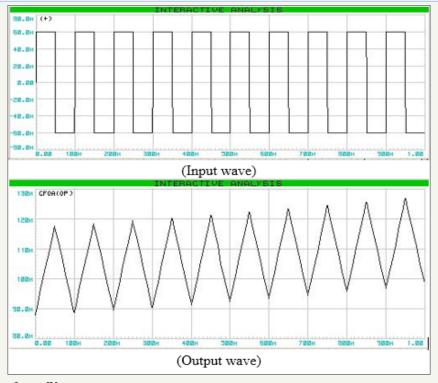


Figure 12: Simulation of case IV.

Wave conversion at 10 Hz by CFOA of Figure 11 using $R_1{=}1000k\Omega,R_2{=}100k\Omega,R_3{=}100k\Omega$, $C_4{=}1uf$

Case V (Integrator 3) Figure 13

When
$$y_1 = sC_1$$
, $y_2 = 0$, $y_3 = \frac{1}{R3}$, $y_4 = sC_4$ using Eq.(1)

$$\frac{Vo}{Vin} = \frac{\text{sC1} - \frac{1}{R3}}{\text{sC1} - \frac{1}{R3} - \text{sC4}}$$

$$\frac{Vo}{Vin} = \frac{\text{sC1} - \frac{1}{R3}}{\text{sC1} - \frac{1}{R3} - \text{sC4}}$$

$$\frac{Vo}{Vin} = \frac{1}{1 - \frac{R3.sC4}{R3.sC1 - 1}}$$

When $C_1 = 1 pF$, $R_3 = 1200 k\Omega$, $C_4 = 1 uf$

$$\frac{Vo}{Vin} = \frac{1}{1 - \frac{1200 \times 10^3 \cdot (s)10^{-6}}{1200 \times 10^3 \cdot (s)10^{-12} - 1}}$$

$$\frac{Vo}{Vin} = \frac{1}{1 - \frac{1.2(s)10^{-6}}{1.2(s)10^{-6} - 1}}$$

Figure 14

Wave conversion at 10Hz by CFOA of Figure13 using $\rm C_1{=}1pF$, $\rm R_3{=}1200k\Omega$, $\rm C_4{=}1uf$.

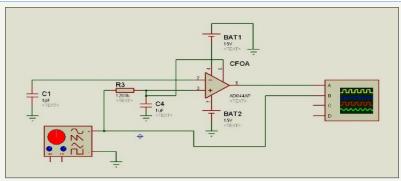


Figure 13: Simulation of case V.

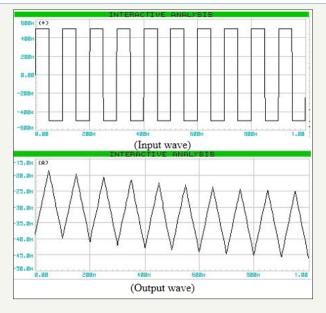


Figure 14: Simulation of case V.

Case VI (Integrator 4) Figure 15

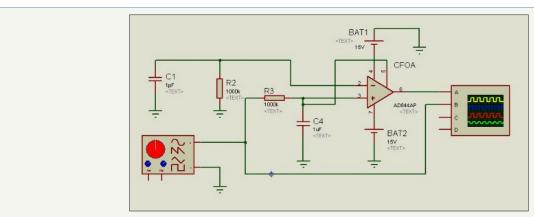


Figure 15: Simulation of case VI.

When
$$y_1 = sC_1$$
, $y_2 = \frac{1}{R2}$, $y_3 = \frac{1}{R3}$, $y_4 = sC_4$ using Eq.(1)

$$\frac{Vo}{Vin} = \frac{sC1 - \frac{1}{R3}}{sC1 + \frac{1}{R2} - \frac{1}{R3} - sC4}$$

$$\frac{Vo}{Vin} = \frac{(R3.sC1 - 1)R2}{R2.R3.sC1 + R3 - R2 - R2.R3.sC4}$$

When
$$C_1$$
=1pF, R_3 =1200k Ω , C_4 =1uf, R_2 =1000k Ω

$$\frac{Vo}{Vin} = \frac{\left(1200\text{k.}(s)10^{-12} - 1\right)10^6}{10^6.10^6.(s)10^{-12} + 1000K - 1000K - 10^6.(s)10^{-6}}$$

$$\frac{Vo}{Vin} = \frac{s - 10^6}{s - 10^6 s}$$

$$\frac{Vo}{Vin} = \frac{1}{1 - 10^6} \left[1 - \frac{10^6}{s} \right]$$

Figure 16

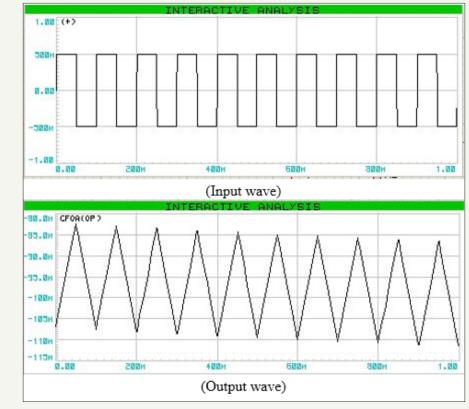


Figure 16: Simulation of case VI.

Wave conversion at 10Hz by CFOA of Figure15 using When C1=1pF, R2=1200k Ω , C4=1uf, R2=1000k Ω

Experimental Result

All the proposed configurations had been tested with Proteus simulation. The AD-844 CFOA was used as the active device. In our experiments, regulated bias voltages were set at 0 ± 12 Vdc. for

the CFOA. Time domain tests for wave conversion measurement were carried out. Some typical results on wave conversion by the integration functions are shown in Table 1. For these tests, the input signals were square wave for the integrators. The gain and frequency had been measured from the oscilloscope display on Proteus simulation. The proposed circuits exhibited satisfactory response practically expected from an integrator.

Table 1: Results (Practical and theoretical values).

Figure No	Value of Passive Components	Grounded Passive Components			Gain	Frequency
		Total Components	R	С	(practical)	(practical)
I	R=10K, C= 9uF	6	2	1	7.14643	32.258Hz
II	R=10K, C= 9uF	6	1	1	0.18875	19.801Hz
III	R ₁ =100k, R ₄ =100k	3	1	1	0.02511	10.106Hz
IV	R ₁ =1000k, R ₂ =100k, R ₃ =100k, C ₄ =1uf	4	2	1	0.46828	9.846Hz
V	C ₁ = 1pF, R ₃ =1200k, C ₄ =1uf	3	0	2	0.01982	10.002Hz
VI	C ₁ =1pF, R ₃ =1200k, C ₄ =1uf, R ₂ =1000k	4	1	2	0.02453	10.002Hz

Conclusion

In this paper, an analysis and simulation is presented about six new cases of active RC integrator circuit realizations, using minimum passive components grounded and a current feedback operational amplifier (CFOA) device are proposed. Integrator with grounded passive components allows better usability in VLSI. The realizability equations are derived and experimental result by wave processing has been verified using Proteus software. The proposed circuits exhibited satisfactory response as practically expected from an integrator.

References

- Nagaria RK (2008) On the new design of CFA based Voltage Controlled Integrator/Differentiator suitable for analog signal processing. WSEAS Transaction on Electronics 6: 232-237.
- Sanyal SK, Sarker UC, Nandi R (1990) Increased time constant dualinput integrators. IEEE Trans on Instrumentation and Measurement 39(4): 672-673.
- 3. Minaei S, Topcu G, Cicekoglu O (2003) Active only integrator and differentiator with tunable time constants. International Journal of Electronics 90(9): 581-588.
- 4. Minaei S (2004) Simple DVCC-based current mode integrators and differentiator Frequenz. Journal of Telecommunication 58(1-2): 41-45.

- Liu SI, Hwang YS (1994) Dual-input differentiators and integrators with tunable time constants using current conveyors. IEEE Trans on Instrumentation and Measurement 43(4): 650-654.
- Minaei S, Sayin OK, Kuntman H (2006) A new CMOS electronically tunable current conveyor and its application to current mode filters. IEEE Transactions on Circuits and Systems 53(7): 1448-1457.
- 7. Venkateswaran P, Nandi R, Das S (2012) New integrators and differentiators using a MMCC. Circuits and Systems 3: 288-294.
- Senani R (1998) Realization of a class of analog signal processing/ signal generation circuits, novel configurations using current feedback operational amplifier. Frequenz 52(9): 196-206.
- Singh AK Senani R (2001) Active R design using CFOA-poles: New resonators, filters and oscillators. IEEE Trans on Circuits and Systems-II 48(5): 504-511.
- Maundy B, Gift SJG, Aronhime PB (2004) A novel differential high frequency CFA integrator. IEEE Trans on Circuits & Systems-I 51(6): 289-293.
- 11. Toumazou C, Lidgey J (1994) Current feedback opamps; A blessing in disguise. IEEE Circuits and Dev Mag 10(1): 34-37.
- 12. Ismail AM, Soliman AM (2000) Novel CMOS current feedback Op-Amp realization suitable for high frequency applications. IEEE Trans Circuit Syst I 47(6): 918-921.
- 13. Mita R, Palumbo G, Pennisi S (2005) Low voltage high drive CMOS Current feedback op-amp. IEEE Trans Circuit Syst II 52(6): 317-321.



Creative Commons Attribution 4.0 International License

For possible submissions Click Here

Submit Article



COJ Electronics & Communications

Benefits of Publishing with us

- · High-level peer review and editorial services
- · Freely accessible online immediately upon publication
- Authors retain the copyright to their work
- Licensing it under a Creative Commons license
- Visibility through different online platforms